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- **Evaluation**. Does this function fit the data well?

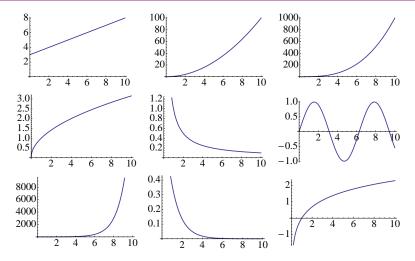
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### Functions you should recognize on sight



TWPS: What are these functions? What is the most general equation?

# Springs and Elongations

Example: Modeling Spring Elongation

Take your favorite spring. Attach different masses. How much does it stretch from rest? [Its **elongation**.]

elong

mass

Χ

50

## Springs and Elongations

What do you notice?

Example: Modeling Spring Elongation

Take your favorite spring. Attach different masses.

How much does it stretch from rest? [Its **elongation**.]

When we plot the data, we get the following **scatterplot**.

Elongation (e	Elo	ngation	of a Sp	oring			
10							
8				. •	•		
4		•	• •				
2	. •	•					
0	100	200	300	400	500	Mass(x)	

50	1.000
100	1.875
150	2.750
200	3.250
250	4.375
300	4.875
350	5.675
400	6.500
450	7.250
500	8.000
550	8.750
	•

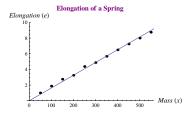
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So: Estimate the slope of the line. How?

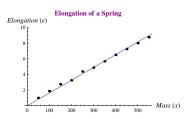
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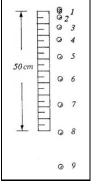
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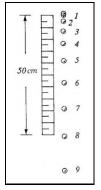
Mathematically: Linear Regression / Least Squares (For another day)

### Example. Modeling the dropping of a golf ball



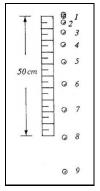
Source: practicalphysics.org

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Use a camera to record the position every tenth of a second.

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50 cm

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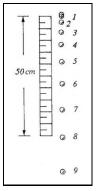
Use a camera to record the position every tenth of a second.

Data would be similar to the table→

t	y
0.0	0.00
0.1	0.25
0.2	0.75
0.3	1.50
0.4	2.50
0.5	4.00
0.6	5.75
0.7	7.75
8.0	10.25
0.9	13.00
1.0	16.00

[Ignore data on p. 25.] [It's BAD data.]

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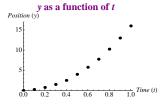
Data would be similar to the table→ lt's plotted in the scatterplot below.

•	•
Position (	ion of a dropped golf ball
15	•
10	•
5	•
0.0	0.2 0.4 0.6 0.8 1.0 Time (t)

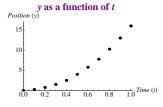
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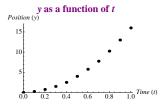


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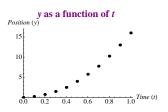
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y as a function of t  Position (y)	0.0		0.00
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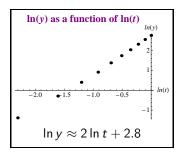
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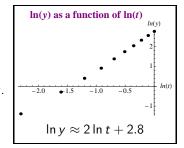


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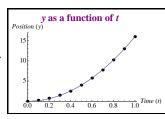
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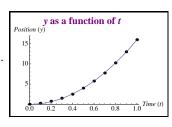
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- Fit the transformed data to a line.
  - $\triangleright$  The slope is an approximation for k.
  - ► The *y*-intercept approximates In *C*.



We have determined that our gravity model  $y(t)=16t^2$  appears to model the dropping of a golf ball.

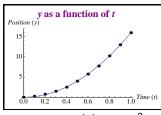


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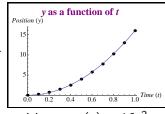
Example. Raindrops

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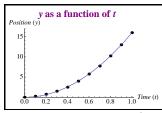


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A raindrop falling from 1024 feet would land after t = 8 seconds.

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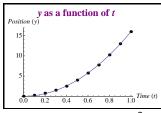
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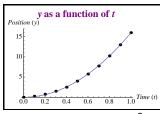
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Even if we have a good model for one situation doesn't mean it will apply everywhere. We always need to question our assumptions.

—Extensive gravity discussion in Section 1.3.—

Example. Modeling the size of a population.

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Definitions: Let t be time in years, t=0 now. P(t)= size of population at time t. P(4)= B(t)= number of births between times t and t+1.  $B(\frac{1}{2})=$  B(5)-D(5)

Therefore, P(t+1) =

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That is, the birth rate  $b = \frac{B(t)}{P(t)}$  and death rate  $d = \frac{D(t)}{P(t)}$  are constants.

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Assumption: No migration.

Therefore,

$$P(t+1) = P(t) \left[ \frac{P(t)}{P(t)} + \frac{B(t)}{P(t)} - \frac{D(t)}{P(t)} \right].$$

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Definition. The **growth rate** of a population is r = (1 + b - d). This constant is also called the **Malthusian parameter**.

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A model for the size of a population is  $P(t) = P(0)r^t,$  where P(0) and r are constants.

## Applying the Malthusian Model

Approximate US Population at: http://www.census.gov/main/www/popclock.htm

Example 1. Suppose that the current US population is 315,400,000. Assume that the birth rate is 0.02 and the death rate is 0.01. What will the population be in 10 years?

Answer. Use  $P(t) = P(0)r^t$ :

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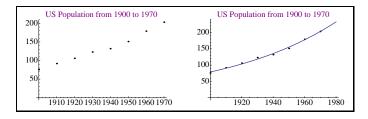
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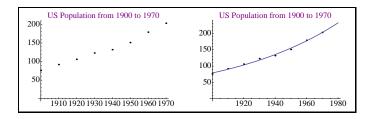
Refinement. (Approx. US Growth Rate at http://www63.wolframalpha.com/input/?i=US+birth+rate

Resource: Wolfram Alpha, integrable directly into Mathematica.

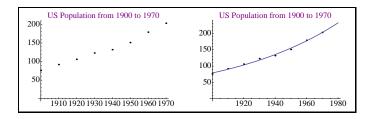
Example 2. How long will it take the population to double?

Answer. Use  $P(t) = P(0)r^t$ :

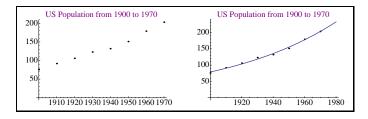




- ▶ Take the logarithm of both sides of  $P(t) = P(0)r^t$ .
- $\blacktriangleright \text{ We have In}[P(t)] = \underline{\hspace{1cm}}$

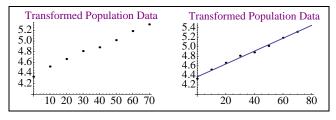


- ▶ Take the logarithm of both sides of  $P(t) = P(0)r^t$ .
- We have ln[P(t)] =
- A linear fit for P(t) vs. t gives values for and

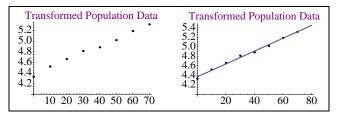


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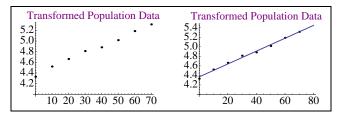


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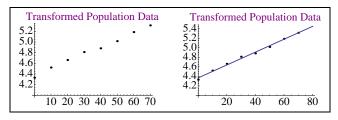
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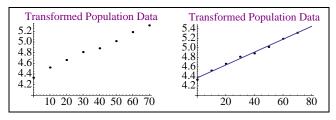


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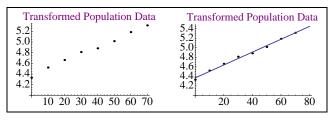
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- $\star$  Important: Transformations distort distances between points, so verification of a fit should always take place on y versus x axes.  $\star$

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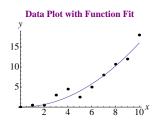
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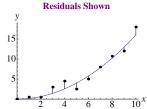
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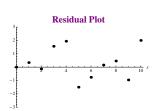
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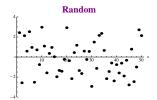




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The structure of the points in the residual plot give clues about whether the function fits the data well. Three common appearances:

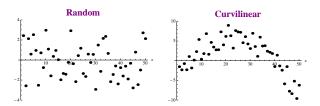
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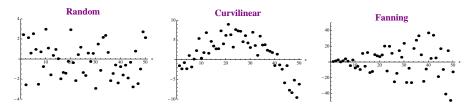
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- Curvilinear: Residuals appear to follow a pattern. Indicates that some aspect of model behavior is not taken into account.
- **Fanning**: Residuals small at first and get larger (or vice versa). Indicates non-constant variability (model better for small x?).



### Interpolation vs. Extrapolation

Suppose you have collected a set of *known* data points  $(x_i, y_i)$ , and you would like to estimate the *y*-value for an *unknown x*-value.

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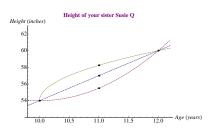
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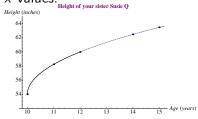
#### Interpolation

Inserting one or more *x*-values between known *x*-values.



#### **Extrapolation**

Inserting one or more *x*-values outside of the range of known *x*-values.



The most common method for interpolation is taking a weighted average of the two nearest data points; suppose  $x_1 < x < x_2$ , then,  $f(x) \sim x_0 + \frac{y_2 - y_1}{x_1}(x_1 - x_2)$ 

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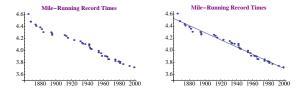
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- ► Confidence in extrapolated data is higher when closer to the range of known *x*-values.

Below is a plot of the years in which a record was broken for running a mile and the record-breaking time.

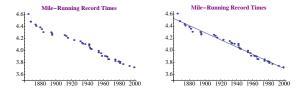


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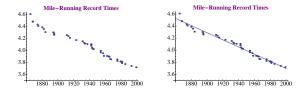
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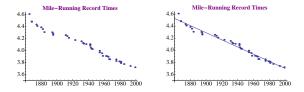
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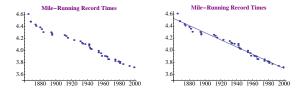
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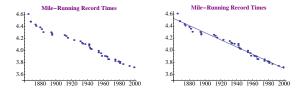


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- Always be careful when you extrapolate!